ILRS SLR MISSION SUPPORT REQUEST FORM (version: January 2018)

SUBMISSION STATUS:
New Submission (default)
O Incremental Submission (accepted only for a follow-on mission; fill-in new information only)
(provide the reference mission and the date approved by the ILRS:
SECTION I: MISSION INFORMATION:
General Information:
Satellite Name: BLITS-M
Satellite Host Organization: Roscosmos, JC "RPC "PSI"
Web Address: www.npk-spp.ru
Contact Information:
Primary Technical Contact Information:
Name: Viktor Shargorodskiy
Organization and Position: JC "RPC "PSI", General designer
Address: 111024, Russia, Moscow, Aviamotornaya street, 53
Phone No.: +7 (495) 234-98-47
E-mail Address: shargorodskiy@npk-spp.ru
Alternate Technical Contact Information:
Name: Andrey Sokolov
Organization and Position: JC "RPC "PSI", Deputy head of the division
Address: 111024, Moscow, Russia, Aviamotornaya street, 53
Phone No.: +7 (495) 988-21-48
E-mail Address: alsokolov@bk.ru
Primary Science Contact Information:
Name: Vladimir Vasiliev
Organization and Position: JC "RPC "PSI", Senior Researcher

Address: 111024, Moscow, Russia, Aviamotornaya street, 53
Phone No.: +7 (495) 707-13-48
E-mail Address: lavaser@kmail.ru
Alternate Science Contact Information:
Name: Andrey Sokolov
Organization and Position: JC "RPC "PSI", Deputy head of the division
Address: 111024, Moscow, Russia, Aviamotornaya street, 53
Phone No.: +7 (495) 988-21-48
E-mail Address: alsokolov@bk.ru
Mission Specifics:
Scientific or Engineering Objectives of Mission:
(specify)
and manufacturd by the JC "Research and production corporation "Precision systems and instruments" under the contract with ROSCOSMOS. The mission purposes are: callibration of the SLR stations, scientific problems solving in geothysics, geodynamics and etc. The "target error" (uncertain of satellite reference point relative to the CoM position) is less than 0.1mm, and the Earth magnetic field does not affect the satellite orbit and spin parameters.
Role of Satellite Laser Ranging (SLR) for the Mission: (specify)
The key role
Anticipated Launch Date: November 2019
Expected Mission Duration: 10 years
Required Orbital Accuracy: During 1-st phase: 50 - 100 m. During the 2-nd phase: 2 mn
Anticipated Orbital Parameters:
Altitude (Min & Max for eccentric orbits): 1500 km

Inclination: 82,5		degrees
Eccentricity: 0		
Orbital Period: 6949	3,5 seconds	
Frequency of Orbital N	Maneuvers: no	
Mission Timeline: (example) Should include when SLR	is to start within the mission time	line, such as "on insertion into orbit" or "launch +N" days.
from the orbital bloc precision orbit deter	ck of the rocket; satellite o rmination; accumulation o ctor satellite position, as w	ellite immediately after launching and separation rbit determination (2-4 weeks). 2-nd phase: f the SLR data for the determination of the rell as for scientific studies in geophysics,
Tracking Requirement	nts:	
Tracking Schedule:	• horizon-to-horizon	custom (specify:)
Spatial Coverage:	• global ILRS network	custom (specify:
Temporal Coverage:	• full-time	custom (specify:)
Normal Point Bin Size	e (Time Span): 30	seconds
(See the "Bin Size" of	other satellites on the ILRS	Justify if other bin size is required.) Web site at s/current_missions/index.html.)
Prediction Center:	"PNBS" of JC "RPC "P	SI"
Prediction Technical C Name: Alexander Z	Zhukov	
Organization and Posi	tion: PNBS" of JC "RP	C "PSI", Director
Address.	24, Russia, Moscow, Av	iamotornaya street, 53
Phone No.: +7 (495		
E-mail Address: mai	l@spnav.ru	
Priority of SLR for PC		Secondary O Backup
Other Sources of POD		
I GNSS I DOR	RIS Accelerometer	other (specify:

her comments of	n mission informati prediction centers and re	on: ferences/links to nor	SLR techniques if	available)	
specify) (list backup	prediction centers and re	Terences/IIIIKS to Hor	I-SER techniques in	avanaoie)	

SECTION II: TRACKING RESTRICTIONS:

Several types of tracking restrictions have been required during some satellite missions. See http://ilrs.gsfc.nasa.gov/satellite missions/restricted.html for a complete discussion.

- 1) Elevation restrictions: Certain satellites have a risk of possible damage when ranged near the zenith. Therefore a mission may want to set an elevation (in degrees) above which a station may not range to the satellite.
- 2) Go/No-go restrictions: There are situations when on-board detectors on certain satellites are vulnerable to damaged by intense laser irradiation. These situations could include safe hold position or maneuvers. A small ASCII file is kept on a computer controlled by the satellite's mission which includes various information and the literal "go" or "nogo" to indicate whether it is safe to range to the spacecraft. Stations access this file by ftp every 5-15 minutes (as specified by the mission) and do not range when the flag file is set to "nogo" or when the internet connection prevents reading the file.
- 3) Segment restrictions: Certain satellites can allow ranging only during certain parts of the pass as seen from the ground. These missions provide station-dependent files with lists of start and stop times for ranging during each pass.
- 4) Power limits: There are certain missions for which the laser transmit power must always be restricted to prevent detector damage. This requires setting laser power and beam divergence at the ranging station before and after each pass. While the above restrictions are controlled by software, this restriction is often controlled manually.

Many ILRS stations support some or all of these tracking restrictions. You may wish to work through the ILRS with the stations to test their compliance with your restrictions or to encourage additional stations that are critical to your mission to implement them.

The following information gives the ILRS a better idea of the mission's restrictions. Be aware that once predictions are provided to the stations, there is no guarantee that forgotten restrictions can be immediately enforced.

Are there any science instruments, detectors, or other instruments on the spacecraft that can be damaged or confused by excessive radiation, particularly in any one of these wavelengths (532nm, 1064nn, 846nm, or 432nm)?

⊙ No	O Yes (specify the instrument or detector in question, providing the wavelength bands and modes of sensitivity.)	
⊙ No	O Yes (specify:	Array) will not be accessible from the ground? to avoid ranging an LRA that is not accessible.)

→ Skip the next questions and go directly to SECTION III if you answered "No" to both of the above questions.

Is th	iere a i	need	I for an elevation tracking restriction? Version 01/2018
O 1	No	0	Yes (What elevation (minimum to maximum in degrees)? degrees)
Is the	ere a n	eed	for a go/no-go tracking restriction?
⊙ N	No	0	Yes (Explain the reason(s)
Is the	ere a n	eed	for a pass segmentation restriction?
O N	No	0	Yes (Explain the reason(s)
Is the	ere a n	eed	for a laser power restriction?
0 N	No		
0 7	Yes		(Under what circumstances?
			(What is the maximum permitted power level at the satellite (nJ/cm ²)?)
			(Is manual control of laser transmit power acceptable? O Yes O No)
			tions to range to satellites with restrictions, the mission sponsor must agree to the ement:
subc	ontrac	tors	sponsor agrees not to make any claims against the station or station contractors or s, or their respective employees for any damage arising from these ranging activities, damage is caused by negligence or otherwise, except in the case of willful misconduct."
Pleas	se pro	vide	e signature to express agreement to above statement:
Sign	ature:		
Date	e:		
Nam	ne (prin	nt):	
Orga	nizati	on a	and Position:
	er con	ıme	ents on tracking restrictions:

SECTION III: RETROREFLECTOR ARRAY INFORMATION:

A prerequisite for accurate reduction of laser range observations is a complete set of pre-launch parameters that define the characteristics and location of the LRA on the satellite. The set of parameters should include a general description of the array, including references to any ground-tests that may have been carried out, array manufacturer and whether the array type has been used in previous satellite missions. So the following information is requested:

Retroreflector Primary Contact Information:
Name: Andrey Sokolov
Organization and Position: JC "RPC "PSI", Deputy head of the division
Address: 111024, Moscow, Russia, Aviamotornaya street, 53
Phone No.: +7 (495) 988-21-48
E-mail Address: alsokolov@bk.ru
Array type:
O Single reflector • Spherical O Hemispherical/Pyramid • Planar
O other (specify:)
O sweet (observe):
Attach a diagram or photograph of the satellite that shows the position of the LRA, at the end of t
document.
★ Attached
E Attached
Attach a diagram or photograph of the whole LRA at the end of this document.
O Attached
Array manufacturer:
JC "Research and production corporation "Precision systems and instruments"
Link (URL and/or reference) to any ground-tests that were carried out on the array:
https://cddis.nasa.gov/lw21/docs/2018/presentations/Session6_Sokolov1_presentation.pd
Has the LRA design and/or type of cubes been used previously?
O No Ses (List the mission(s): BLITS

For accurate orbital analysis it is essential that full information is available in order that the 3-dimensional position of the satellite center of mass may be referred to the location in space at which the laser range measurements are made. To achieve this, the 3-D location of the LRA phase center must be specified in a satellite-body-fixed reference frame with respect to the satellite's mass center. In practice this means that the following parameters must be available at 1 mm accuracy or better.

Define the satellite-body-fixed XYZ coordinates (i.e. origin and axes) on the spacecraft: (specify) (add a diagram in the attachment)

XYZ coordinates: (
including the attitude control policy: (specify) (add a diagram in the attachment) The 3-D location of the satellite's mass center in satellite-body-fixed XYZ coordinates is: Always fixed at (0, 0, 0) Always fixed at (reference point of the retroreflector is 110,343 mm behind the sphere center. The range
including the attitude control policy: (specify) (add a diagram in the attachment) The 3-D location of the satellite's mass center in satellite-body-fixed XYZ coordinates is: Always fixed at (0, 0, 0) Always fixed at (
 ⚠ Always fixed at (0, 0, 0) ☐ Always fixed at (including the attitude control policy:
 ♠ Always fixed at (0, 0, 0) ♠ Always fixed at (
 ♠ Always fixed at (0, 0, 0) ♠ Always fixed at (
 ♠ Always fixed at (0, 0, 0) ♠ Always fixed at (
 ⚠ Always fixed at (0, 0, 0) ☐ Always fixed at (
 ○ Time-varying by approximately () mm during the mission lifetime. Will a time-variable table of the mass center location be available on the web? ○ No ○ Yes (URL:) The 3-D location (or time-variable range) of the phase center of the LRA in the satellite-body-fixed XYZ coordinates: (• Always fixed at (0, 0, 0)
Will a time-variable table of the mass center location be available on the web? No Yes (URL: The 3-D location (or time-variable range) of the phase center of the LRA in the satellite-body-fixed XYZ coordinates: (O Always fixed at (,) in mm
The 3-D location (or time-variable range) of the phase center of the LRA in the satellite-body-fixed XYZ coordinates: (Will a time-variable table of the mass center location be available on the web?
XYZ coordinates: (0 110 (c.12)
The following information on the corner cubes must also be supplied. The XYZ coordinates referred to in the following are given in: Satellite-body-fixed system (same as above) LRA-fixed system (specify below)	The 3-D location (or time-variable range) of the phase center of the LRA in the satellite-body-fixe
The following information on the corner cubes must also be supplied. The XYZ coordinates referred to in the following are given in: Satellite-body-fixed system (same as above) LRA-fixed system (specify below)	XYZ coordinates:
The XYZ coordinates referred to in the following are given in: Satellite-body-fixed system (same as above) LRA-fixed system (specify below)	(,) in mm
Satellite-body-fixed system (same as above)LRA-fixed system (specify below)	The following information on the corner cubes must also be supplied.
Satellite-body-fixed system (same as above)LRA-fixed system (specify below)	The XYZ coordinates referred to in the following are given in:
	Satellite-body-fixed system (same as above)
	(speerly the origin and orientation) (and a diagram in the diagram)
	·

angles or normal vect the angles should be c	or) and the clocking (horizontal rotation) angle of each corner cube. No learly defined.	ote that
	d of this document table for small number (10 or fewer) of corner cubes) fram in the attachment)	
N/A		
	ssed in its container (i.e. can the container obscure a part of the corner cubecify below)	ne)?
(specify) (add a diagram)		
N/A		
The size of each corne	r cube: Diameter (N/A) mm Height (N/A) mm	
The material from whi	ch the cubes are manufactured (e.g. quartz):	
The refractive index of		
AL/A	for wavelength $\lambda = 0.532$ micron	
= <u>N/A</u>	as a function of wavelength λ (micro	n):
The group refractive in	idex of the cube material, as a function of wavelength λ (micron):	
NI/A	for wavelength $\lambda = 0.532$ micron	
= N/A	for wavelength $\lambda = 0.332$ finction as a function of wavelength λ (micro	m):
	as a function of marciengin it (infere	/-

List the position (XYZ) of the center of the front face of each corner cube, and the orientation (two

Dihedral angle offset(s) and manufacturing tolerance (in arcseconds): N/A	Version 01/2018
Radius of curvature of front surfaces of cubes:	
Not applied)
Flatness of cubes' surfaces:	
N/A	
Back-face coating:	

Other comments on LRA:

Uncoated

(specify) (add a reference to a study of the optical response simulation/measurement if available) (add a diagram if applicable)

O Coated (specify the material:

The BLITS-M consist of two radiation resistant hemispheres made of a low-refraction-index glass type K-108 (optical characteristics correspond to the SHOTT glass N-BK7) and an inner ball lens made of a high-refrection-index glass ΤΦ-105 (optical characteristics correspond to the SHOTT glass N-SF4). The ball lens radius is 64.008 mm. The total radius of the sphere reflector is 110.343 mm. The hemispheres are glued over the ball lens; the external surface of one hemisphere is covered with an dielectric coating. The dielectric coating reflects the laser radiation at the wavelength of 532 nm (See attachment).

SECTION IV: MISSION CONCURRENCE

301-614-6542 (Voice) 301-614-6015 (Fax) Carey.Noll@nasa.gov

The ILRS is a voluntary organization that operates under the auspices of the International Association of Geodesy (IAG). The ILRS adheres to the IAG policy to make all acquired laser ranging data and derived products publicly available. We request that the mission website, as well as mission publications, reference the scientific work derived from ILRS data and derived products, **acknowledge** the role of the ILRS. This acknowledgment is crucial for the continued support from the funding agencies of the ILRS participating organizations.

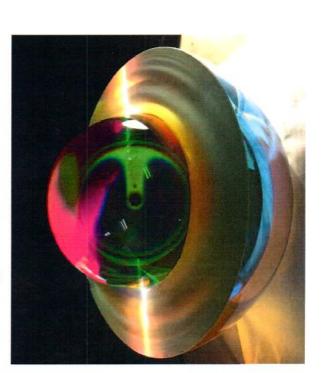
ive of the BLITS-M	mission, I hereby
RS to track the satellite described in this document.	
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SECTION V: ATTACHMENT(S)

BLITS-M



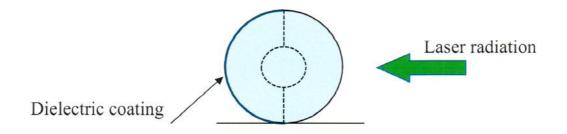
Hemisphere of the BLITS-M



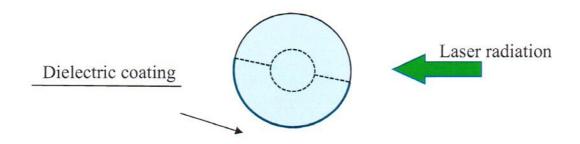
Hemisphere with lens ball

Reflection index of the BLITS dielectric coating for:

1. The laser radiation falls on the center of the transparent hemisphere



2. The laser radiation falls on the area between two hemispheres



Reflection,% R = 98 % $\lambda = 532 \text{ nm}$ 700 λ, nm

Refraction index n_{λ} and group refraction index n_g for N-BK7 and SF4 glasses



