

# A New Toolset for Passive Monitoring of Air Traffic and Sky Conditions at Metsähovi Station, Finland

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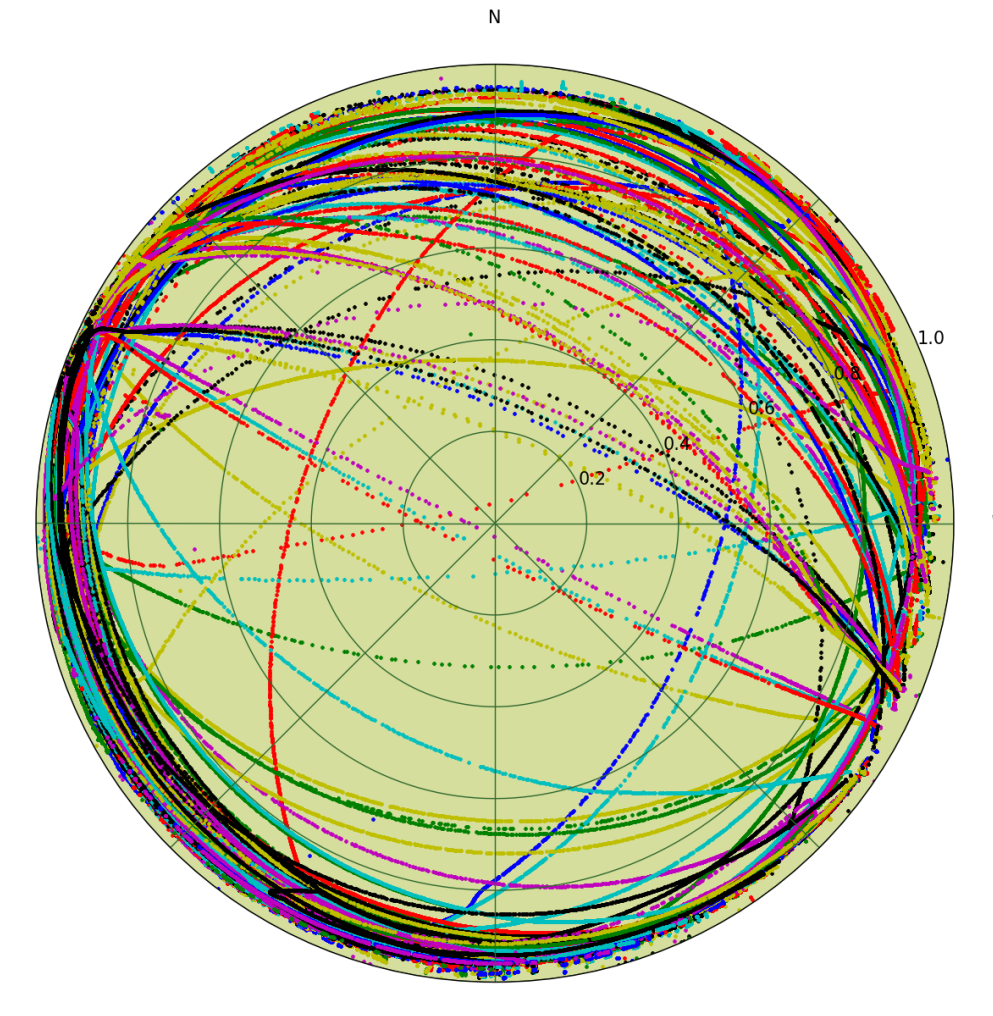
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## Introduction

Metsähovi Geodetic Research Station in Southern Finland is located near the Helsinki International Airport. Some of the flight patterns to the airport enter directly to Metsähovi airspace. Robust solutions for airplane laser safety are called for. The new Metsähovi SLR system (first light due 2015) is located a few hundred meters from Metsähovi VLBI antenna and therefore active radio frequency based methods for aircraft detection (i.e., radar) are not allowed. To address the airplane safety issue and to provide the SLR operator with a tool for monitoring the observing conditions, several auxiliary sensors/systems have been obtained for Metsähovi. Here we introduce the systems and how we have integrated them into a tool for the observer.

## AirNav RadarBox 3D

In 2013 we acquired an AirNav RadarBox 3D Mode-S/ADS-B receiver which we use to track commercial air traffic over Southern Finland in real time. RadarBox provides real-time 3D position information for airplanes that transmit Mode-S/ADS-B data. The receiver comes with its own GUI, but the data is also provided in XML format for use in other applications.



All airplane tracks over Metsähovi during June 1<sup>st</sup> 2014. Most of the planes fly at apparent low altitudes, but several cross also the zenith. As the ADS-B data is sent at 2 Hz rate, there appears to be gaps in the data near the zenith where the apparent speed of the airplanes is the greatest.

## Alcor System OMEA All Sky Camera

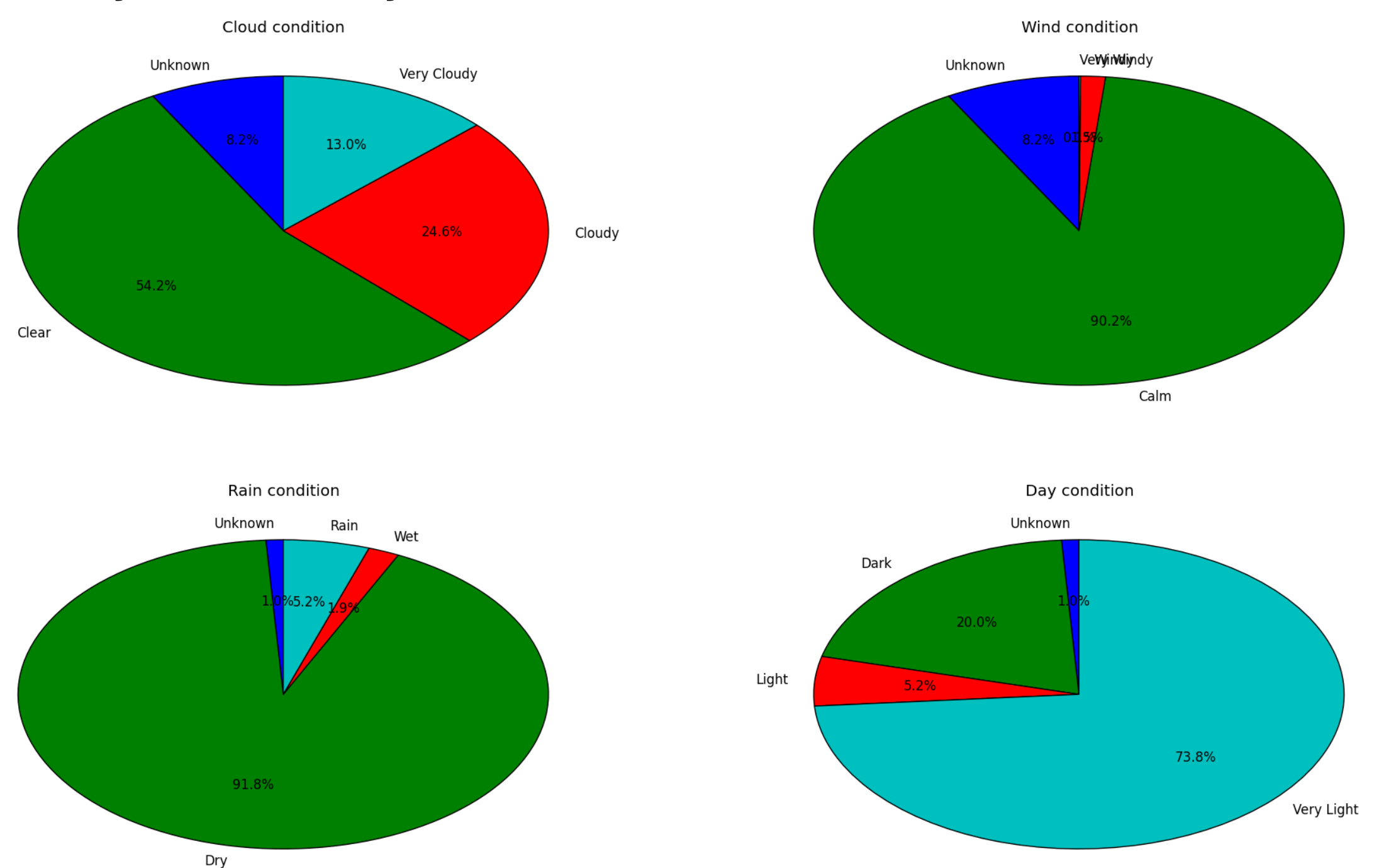
Also in 2013 we acquired an OMEA all-sky camera that can provide correctly exposed 2 Mpix 185° fish-eye color images both day and night, i.e., it has an adjustable aperture. These images can, especially during the day, be used to identify satellites that are not in clouded regions of the sky nor (with the aid of overlaid Airnav Radarbox data) close to airplanes. The telescope pointing direction and satellite tracks from the latest CPF files are plotted to the all-sky image with the help of a custom written Python program.

## Boltwood Cloud Sensor II

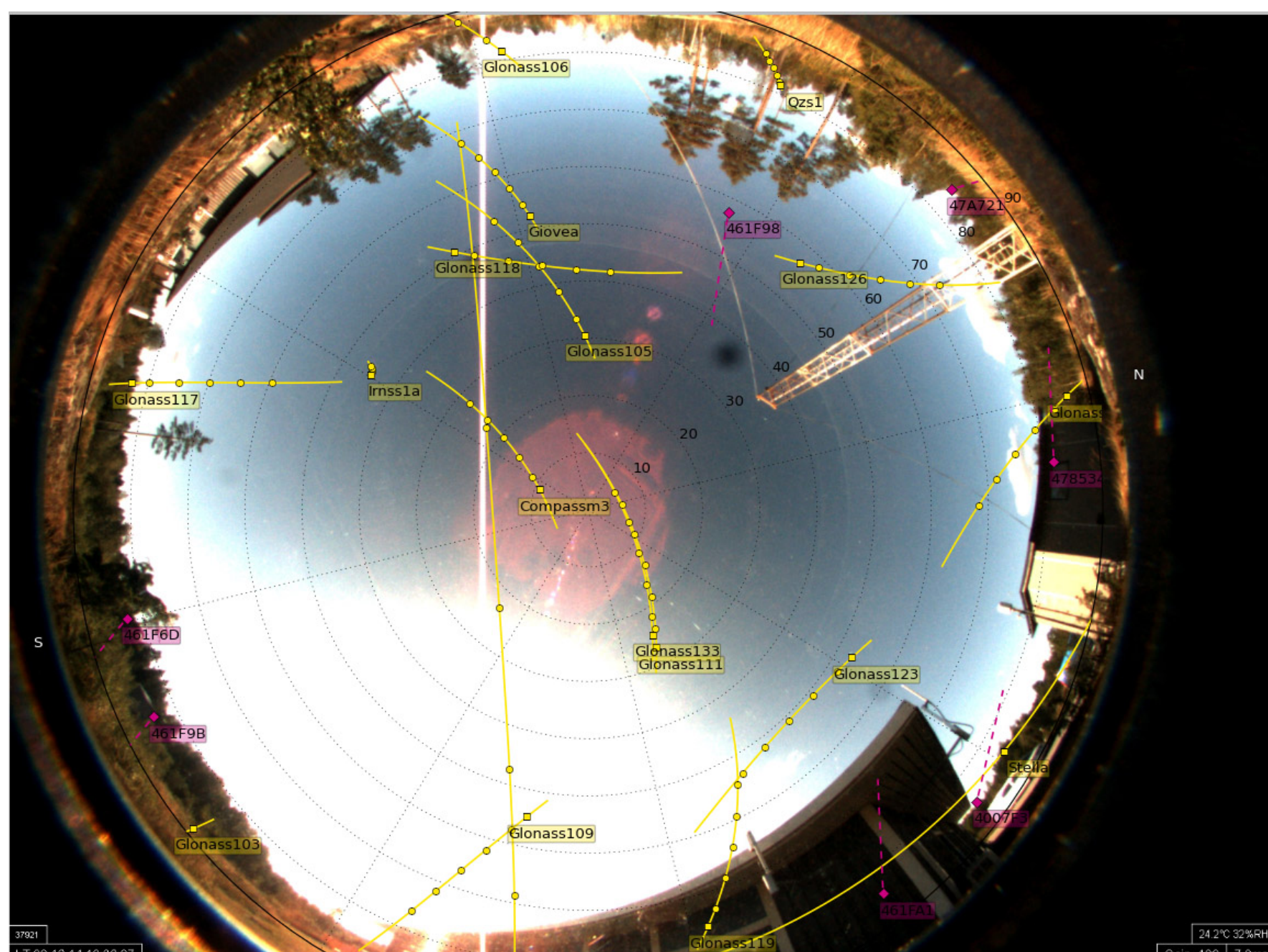
We acquired a Boltwood Cloud Sensor II for monitoring the sky conditions in Metsähovi. The unit measures several meteorological parameters (wind speed, rain, humidity, etc.) as well as sky temperature vs. ambient temperature for cloudiness index determination. These measurements provide the operator a clear view of the current sky condition. Cloudiness index is especially useful for night time operations, where the cloud situation is not readily seen from the all-sky image. When weather conditions are adverse to SLR operations, the operator can concentrate on other tasks, while being immediately alerted when the weather improves. The cloud sensor is also used to provide weekly and monthly weather statistics in Metsähovi.

## Python-based tool

To provide a single tool for the operator, we have developed a Python-based program which plots the airplane positions and directions to an all-sky image obtained with the OMEA camera. In addition to the airplane positions, also the tracks and positions of satellites over the Metsähovi horizon and the telescope pointing direction are plotted to the all-sky image. An alarm is rung if an aircraft is within a user-defined distance from the pointing direction of the telescope. As the all-sky image is semi-realtime, this tool can also be used to identify satellites that are in a cloud-free part of the sky.



Weather conditions in Metsähovi during the summer of 2014 (15<sup>th</sup> May-14<sup>th</sup> August). Boltwood Cloud Sensor categorizes the conditions in five categories. Category "unknown" is mainly used in heavy rain that makes the use of, e.g., the bolometer impossible.



An example screenshot of an all-sky image overlaid with satellite and airplane position and direction data.

## Conclusions and future work

Most likely, no single passive system can achieve SLR airplane safety alone and several complementary systems are required. E.g., an ADS-B receiver can only provide information about airplanes that transmit ADS-B data. Small airplanes, helicopters, hot air balloon, military airplanes, etc. do not send ADS-B data and further methods need to be explored to make the system safe for them as well.