



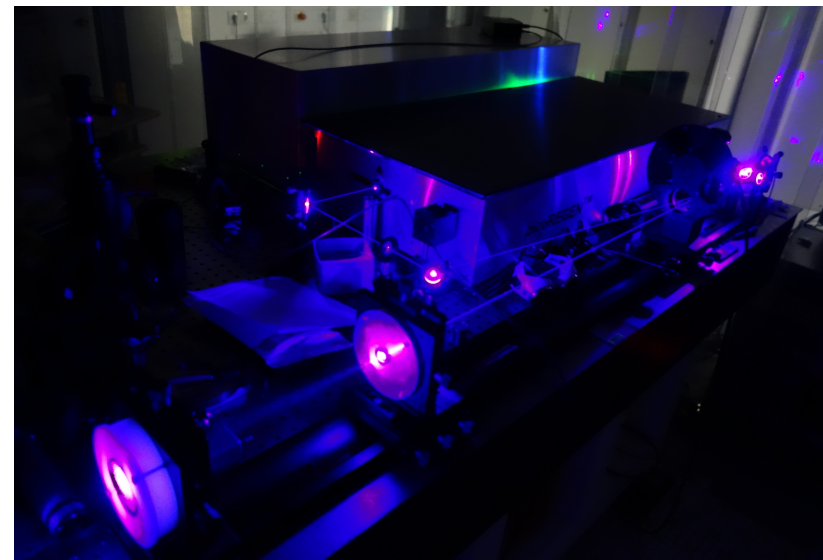
FIRST RESULTS FROM THE SATELLITE OBSERVING SYSTEM WETTZELL

**S.Riepl, A.Böer, R.Dassing, U.Hessels, J.Eckl, A.Leidig, R.Motz,
S.Mähler, C.Schade, M.Schönberger, T.Schüler**

Bundesamt für Kartographie und Geodäsie
Geodätisches Observatorium Wettzell



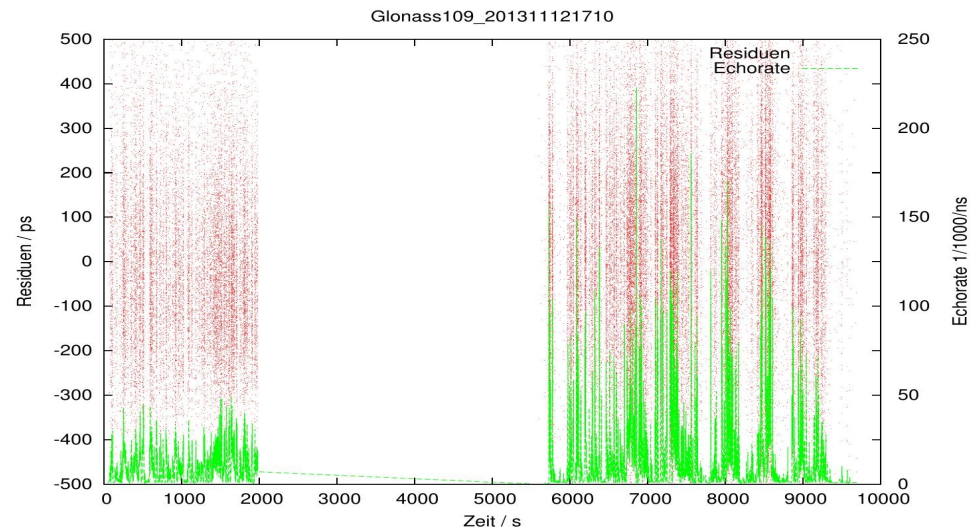
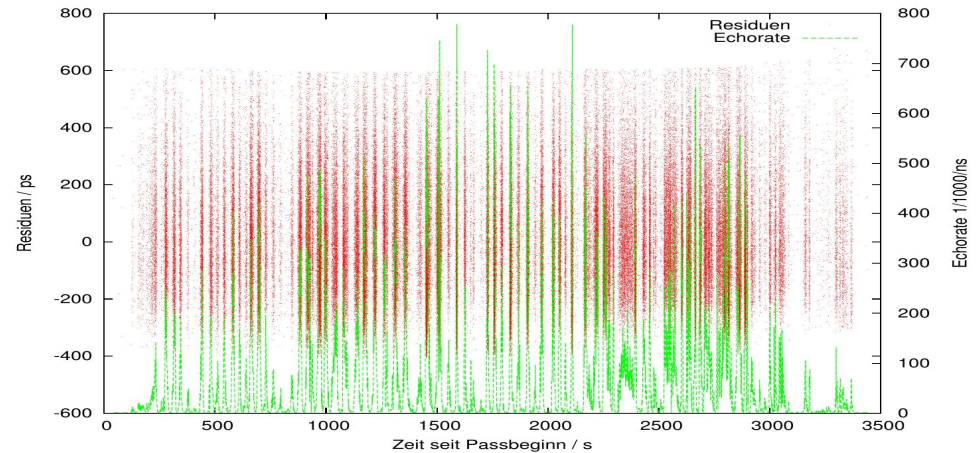
- bistatic kHz-SLR System
- strict single photoelectron mode
- 15 cm transmit, 50cm receive aperture
- support for simultaneous two color measurements @ 849.8nm and 424.9nm
- diverse calibration modes for range and star calibration
- local tie monitoring with parallax compensation
- pointing corrections by active optics
- event timing system
 - based on Dassault counters
 - synchronized to local MASER
- Integrated aircraft safety LIDAR at eyesafe wavelength





Real first light with nominal transmit telescope

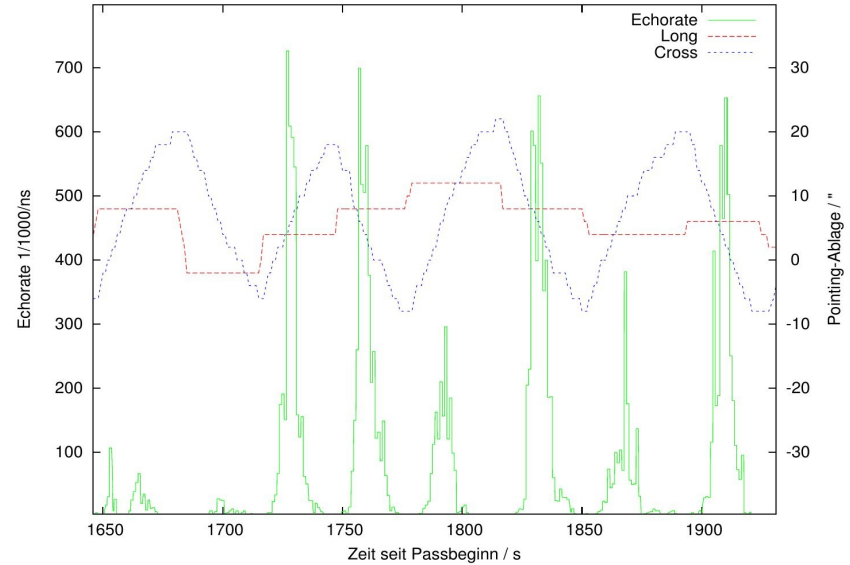
- Long-cross offsets shifted periodically around satellite position
- Up to 80% returnrate for Lageos, 25% for Glonass
- Lageos observations down to 15° elevation (saftey limit)
- Glonass observations down to 20° elevation possible



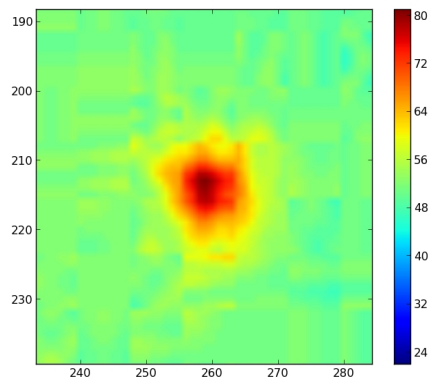


laser collimation / transmit telescope diagnostic

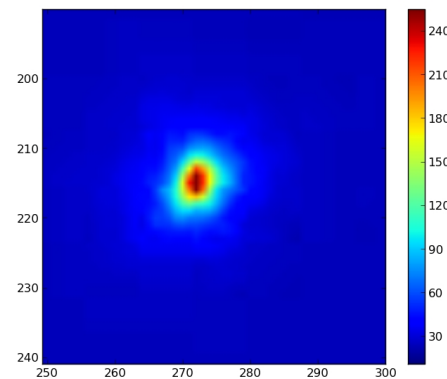
- Laser divergence from signal strength vs. offset measurement $< 5''$
- Star images (25"x25") recorded through transmit optics:
 - $< 3''$ FWHM @ 850nm
 - $< 4''$ FWHM @ 425nm



Star Image 425nm

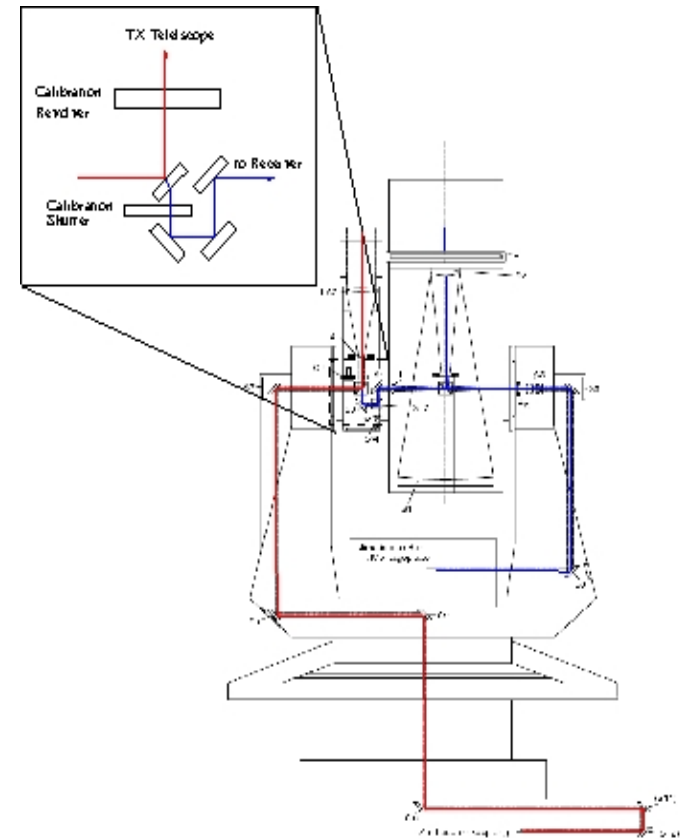


Star Image 850nm



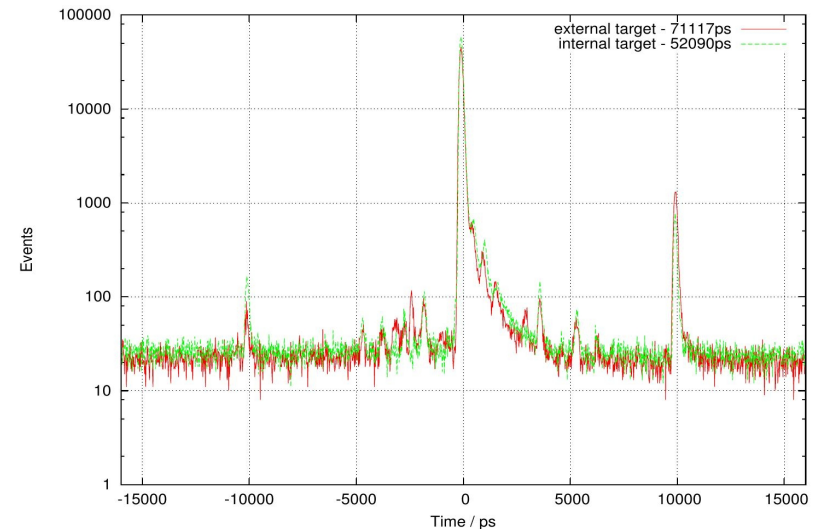
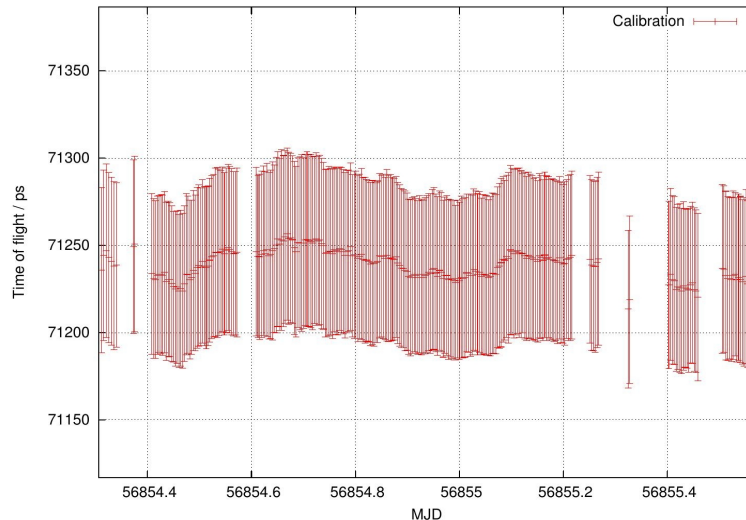
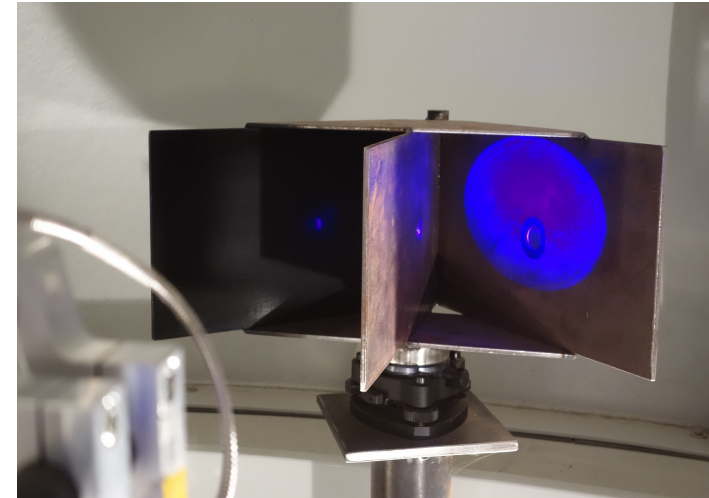


- Optics optimized for 850nm, 425nm and 532nm
- Spectral filtering down to 0.05nm
- Spatial filtering down to 15"
- Piezo elements for
 - Coude/Laser alignment
 - TX/RX alignment
 - aberration compensation
- all alignment monitored by a single camera
- Detectors in Nasmyth climate box



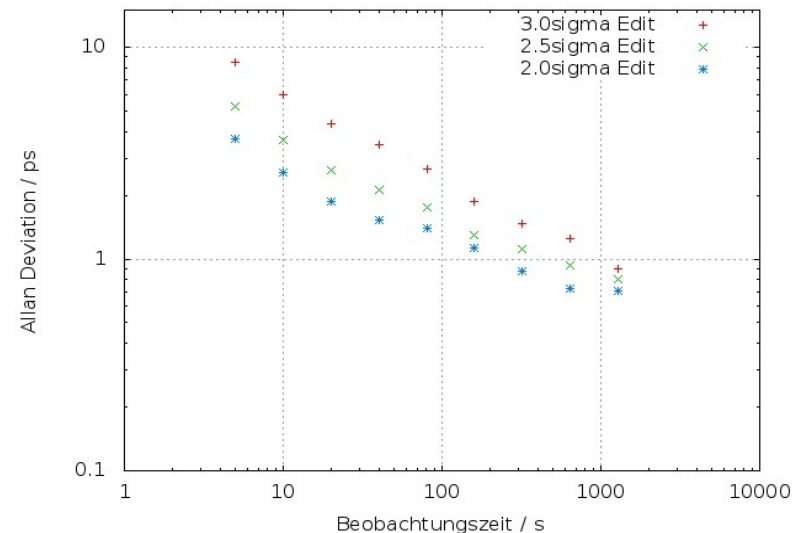
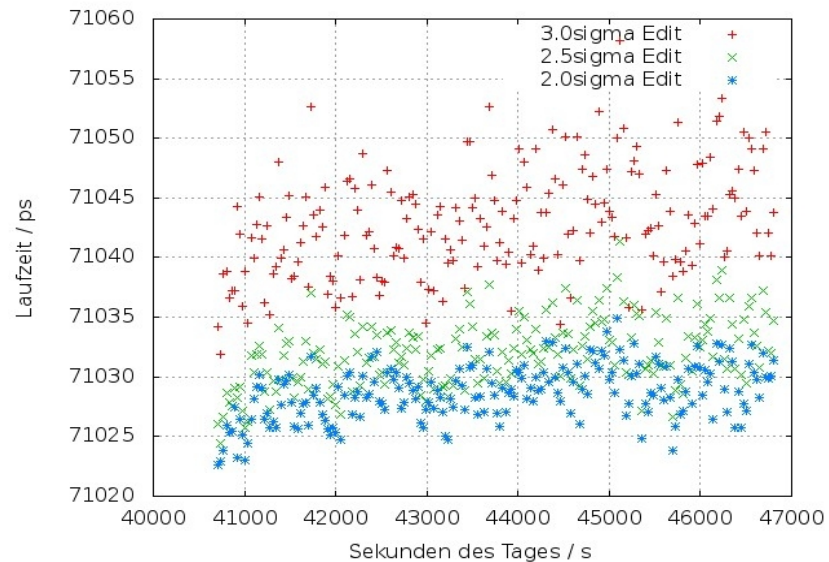


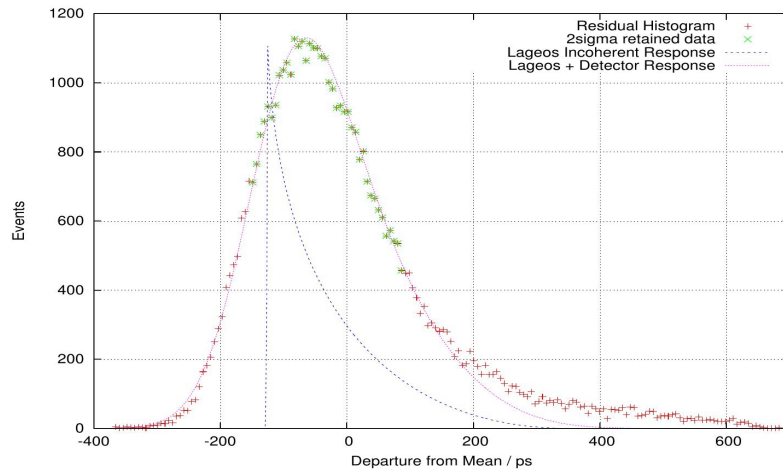
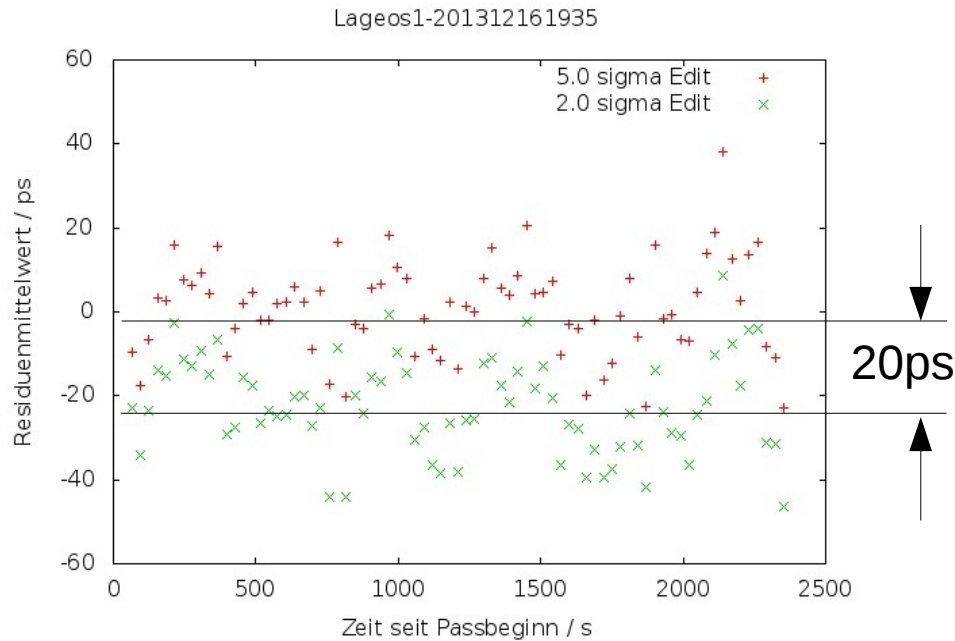
- absolute calibration by optical square
- primary calibration method
- prepulse and straylight isolation
< 1:500 at fundamental wavelength !
- maximum drift <10ps/h





- New avalanche diode with 500 μ m diameter and sufficient timing characteristics
- 2 sigma editing \rightarrow 40ps rms
- What is the best averaging time for which editing level ?
- Less than 2 sigma editing leads to instability
- Noise floor \sim 700fs reached in 600s
- submillimetric stability for all current normal point intervals
- Smaller single shot rms highly desirable for two colour ranging



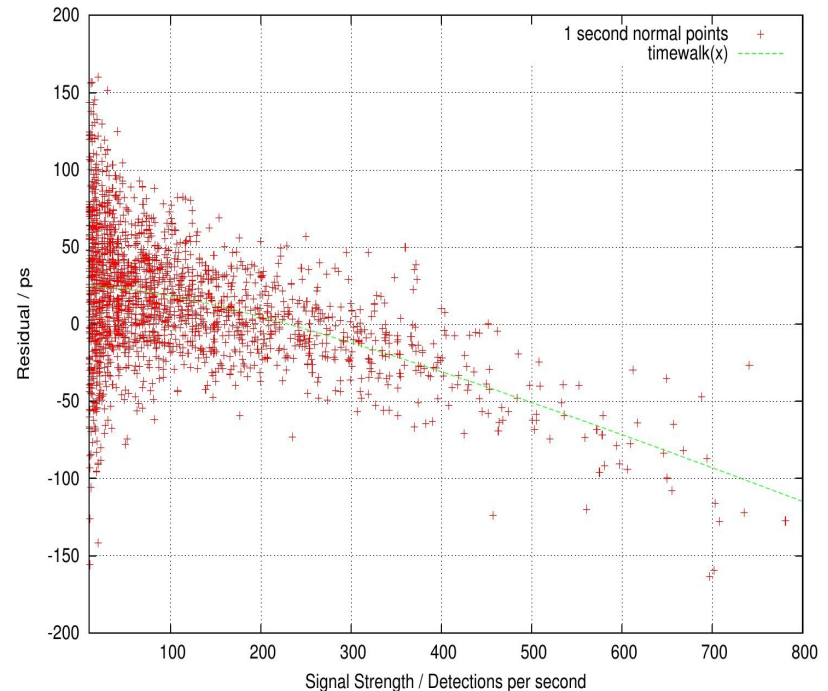


- Lageos single pe rms 120ps
- iterative 2 sigma editing → 60ps
- mean shift of 20ps between 5 and 2 sigma edit
- agreement with incoherent response (Fitzmaurice 1977)
- deduced center of mass correction 247mm @850nm
- Poisson statistics contribution ~ 0.6mm



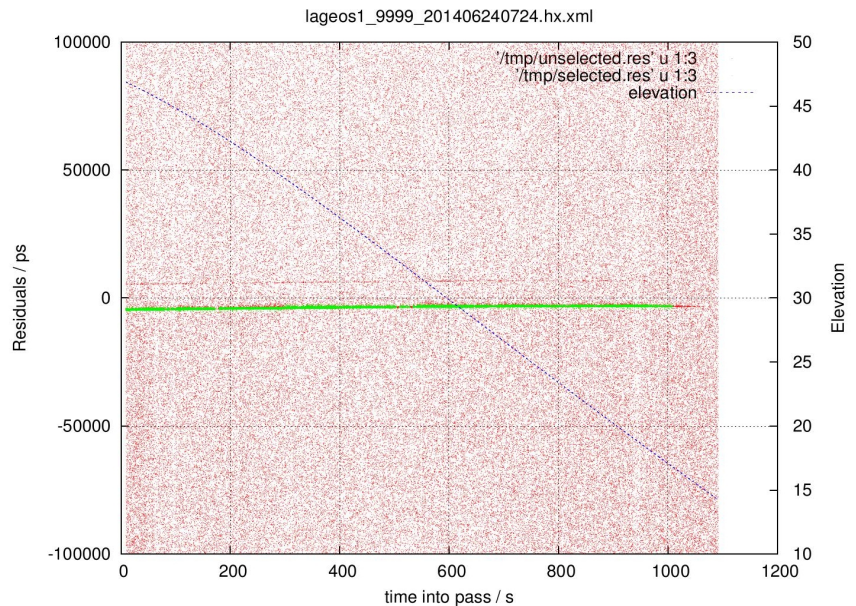
SAP500 - Timewalk analysis within a second

- Lageos 1 second normal points
- logarithmic model
 - TW(1%,...,10%)~6ps
 - TW(10%,...,20%)~13ps
 - TW(20%,...,100%)~165ps
- current return rate filter accepts signal levels from 1% to 20% return rate (strict SPE mode)
- calibration signal level kept at 10% return rate





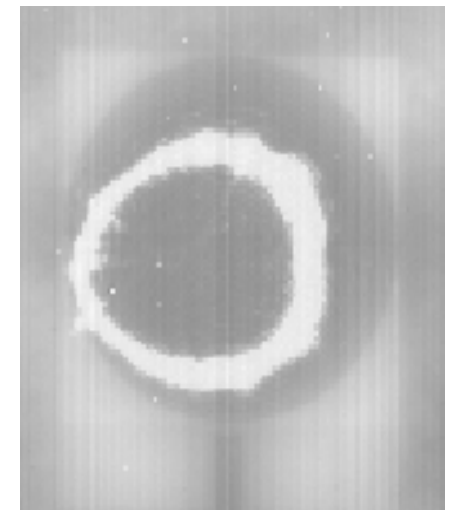
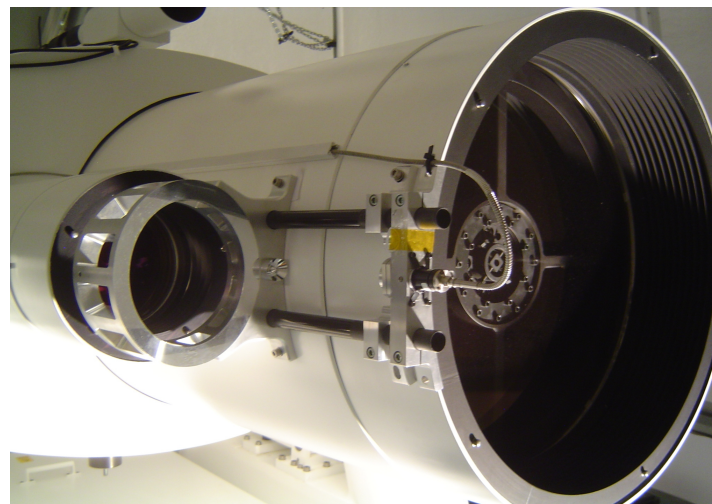
- 1nm FWHM spectral filter
- 15" spatial filter, close to velocity aberration angle
- daylight noise < 0.5% per 1 ns binwidth
- repetition rate kept constant
- transmit/receive time overlap
backscatter reduced to minimum
- with sufficient Coude-alignment
satellites are acquired without
pointing corrections





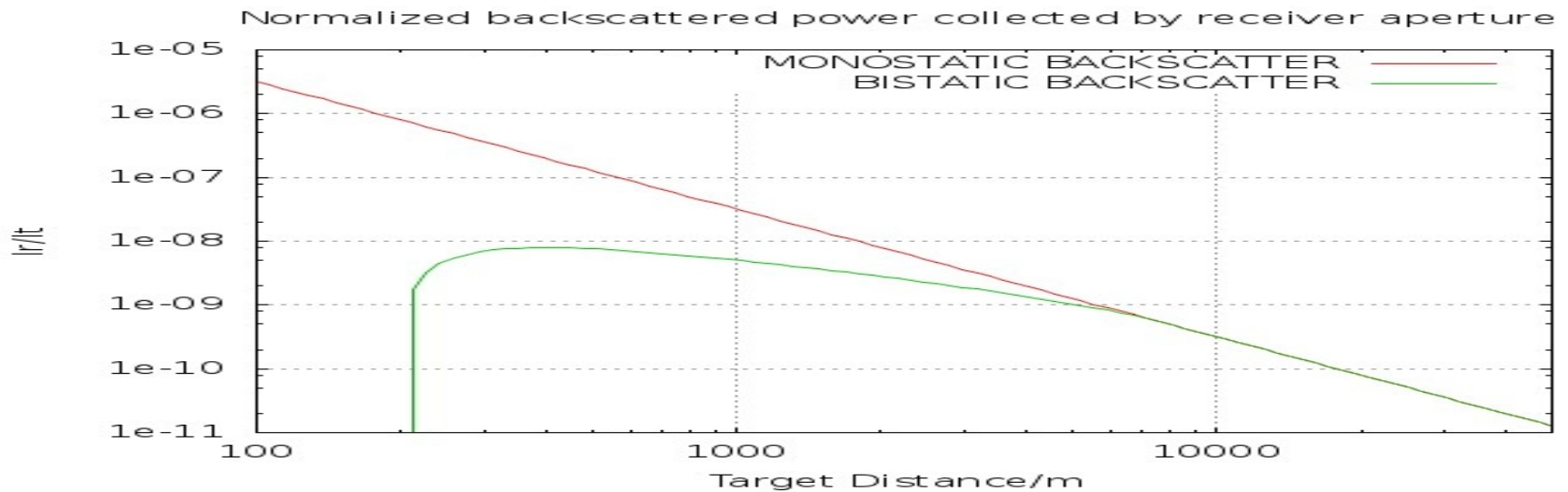
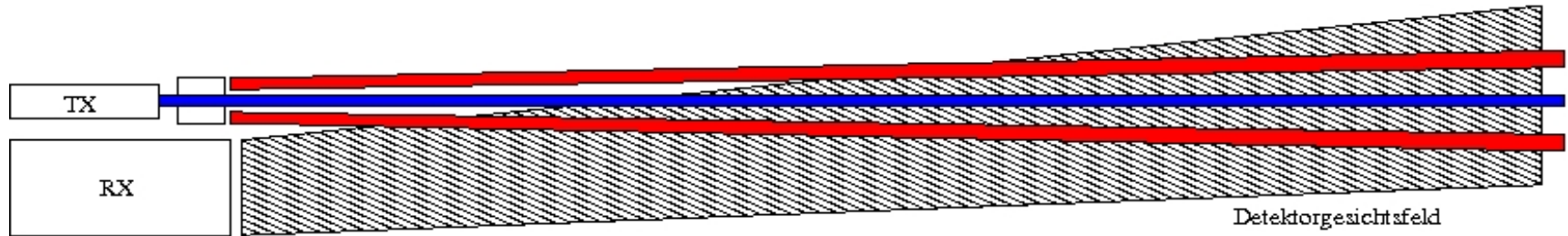
Aircraft Safety Concept

- Aircraft position and velocity data from Federal Aviation Office
- ADS-B data
- Aircraft Safety LIDAR (ASL)
 - primary safety device
 - VLBI 2010 compatible
 - hardwired circuits only
 - maximum object distance 25km (projected)





Aircraft Safety LIDAR - Linkbudget

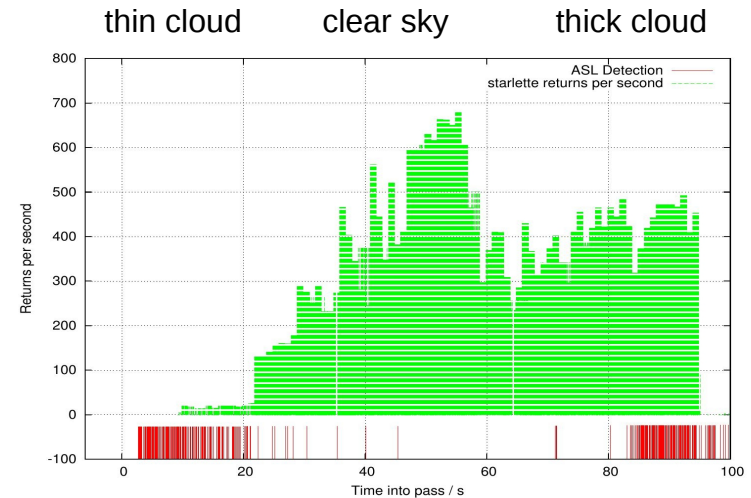
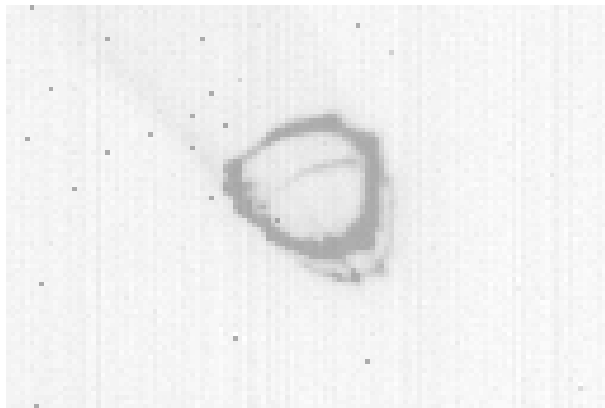


- Detector NEP 0.4pW @ 1kHz, uncooperative target backscatter @ 4.8km distance → 5mV
- geometric compression by limited detector field of view, near field sensitivity via secondary scattering
- integrated Rayleigh backscattering (1.2-50km) $< 1.5E-14$
- integrated MIE backscattering (1.2-50km) approx. $8E-10$ (light haze)



Aircraft Safety LIDAR - Verification

- basic verification on distant groundtarget
- cloudtracking
- tracking Starlette through cloud fields
- aircraft or UAV tracking to verify far field sensitivity and detection delay





Conclusion and Outlook

- collected more than 200 passages in 2014, analysis by Horst Müller and Daniela Thaller
- data delivery quarantine status
- all ILRS satellite missions observed consistently
- linkbudget for 850nm ensures GNSS observations down to 20° Elevation
- still waiting for
 - final redesign of transmit optics
 - final replacement of elevation drive
- expected to be operational in early 2015
- subsequent implementation of two colour ranging mode

